EE 508

Lecture 37

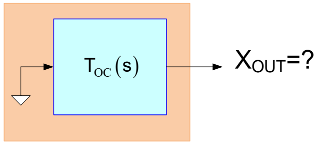
Oscillator/VCO-Derived Filters

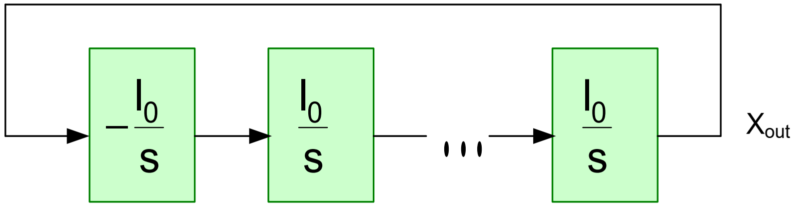
Review from last lecture:

Oscillator Background:

Consider a cascaded integrator loop comprised of n integrators

This structure is often used to build oscillators





(assume an odd number of inverting integrators)

$$X_{OUT} = -\left(\frac{I_0}{s}\right)^n X_{OUT}$$

$$X_{OUT}\left(s^n + I_0^n\right) = 0$$

$$D(s) = s^n + I_0^n$$

Review from last lecture:

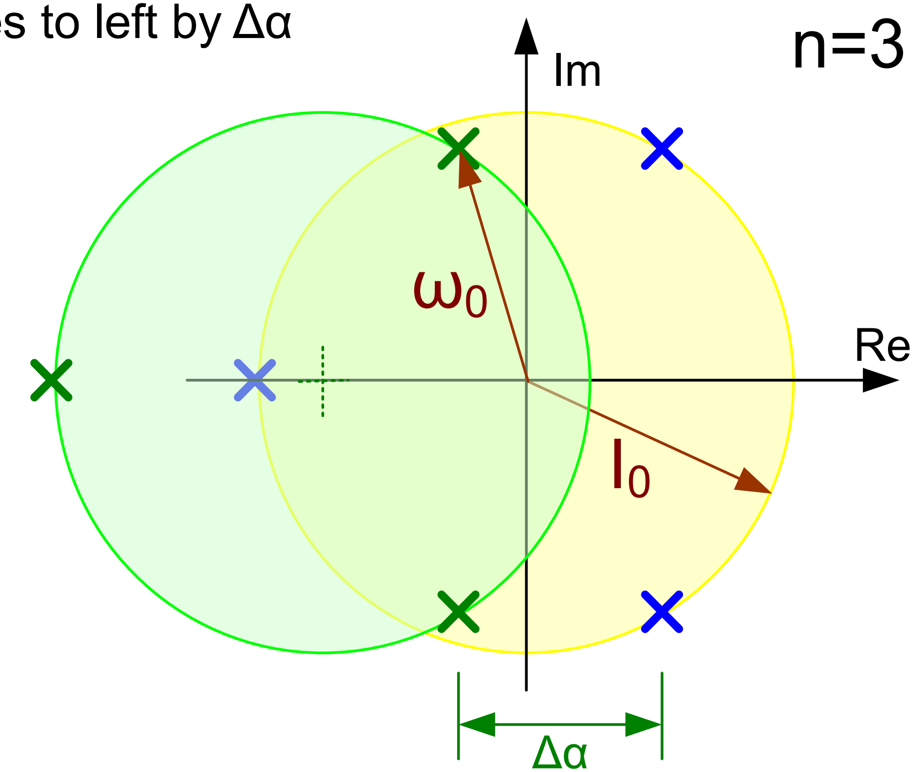
Consider the following 3-pole situation

Poles of $D(s) = s^n + I_0^n$

Consider moving all poles to left by Δα

$\beta = 0.866\ I_0$

$\alpha = 0.5\ I_0 - \Delta\alpha$



$$\omega_0 = \sqrt{\alpha^2 + \beta^2}$$

So since α is fixed , to get a high ω_0, want β as large as possible

Consider now the filter obtained by adding a loss of α_L to the integrators

Will now determine α_L and I_0 needed to get a desired pole Q and ω_0 by moving all poles so that right-most pole pair is the dominant high-frequency pole pair of the filter

The values of α and β are dependent upon I_0 but the angle θ is only dependent upon the number of integrators in the oscillator or VCO

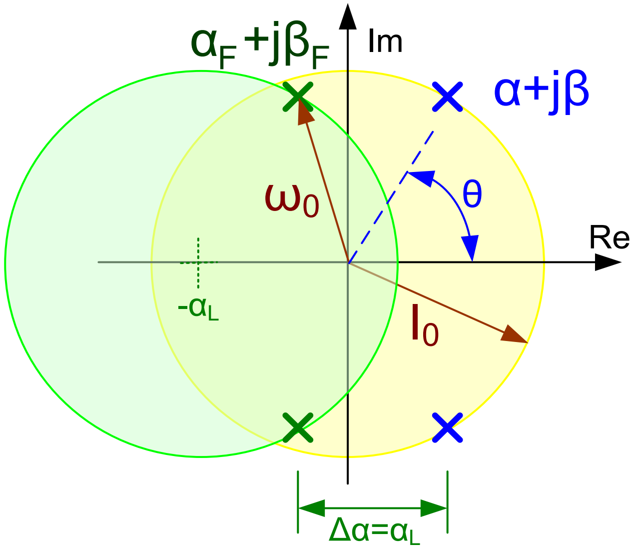
$$\alpha + j\beta = I_0(\cos\theta + j\sin\theta)$$

Define the location of the filter pole to be

$$\alpha_F + j\beta_F$$

It follows that

$$\beta_F = \beta \qquad \alpha_F = \alpha - \alpha_L$$



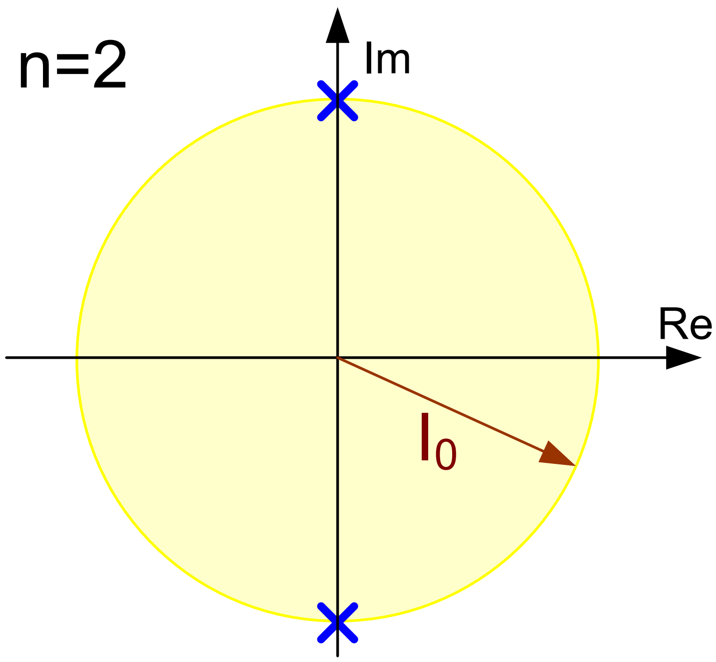
The relationship between the filter parameters is well known

$$\beta_F = \frac{\omega_0}{2Q}\sqrt{4Q^2 - 1} \qquad \alpha_F = -\frac{\omega_0}{2Q}$$

Thus for any n

$$I_0 = \frac{\omega_0}{(\sin\theta)2Q}\sqrt{4Q^2 - 1} \qquad \alpha_L = \frac{\omega_0}{2Q} + I_0\cos\theta = \frac{\omega_0}{2Q} + \frac{\omega_0}{2Q(\tan\theta)}\sqrt{4Q^2 - 1}$$

Will a two-stage structure give the highest frequency of operation for integrators with unity gain frequency I_0?

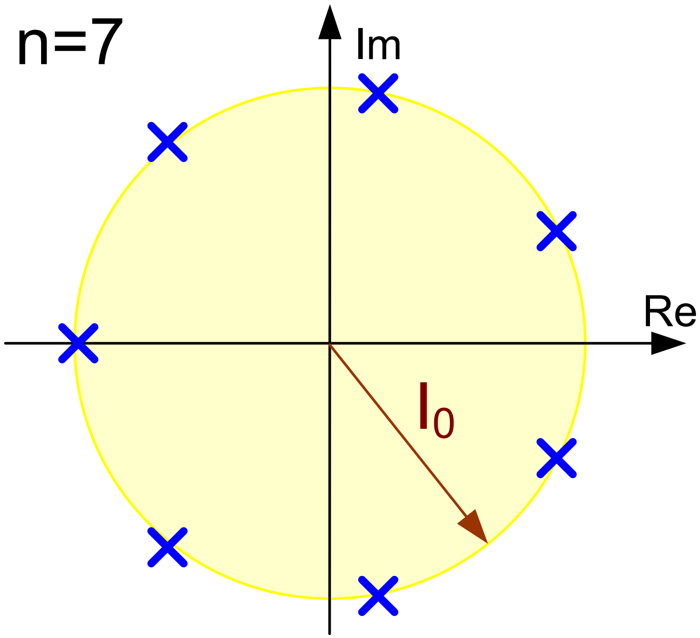


$$\omega_0 = \sqrt{(\alpha - \Delta\alpha)^2 + \beta^2} \longrightarrow \omega_0 = \sqrt{(-\Delta\alpha)^2 + \beta^2}$$

- Even though the two-stage structure may not oscillate, can work as a filter!
- Need odd number of inversions in integrators
- Can add phase lead if necessary

Oscillator Background:

What will happen with a circuit that has two pole-pairs in the RHP?

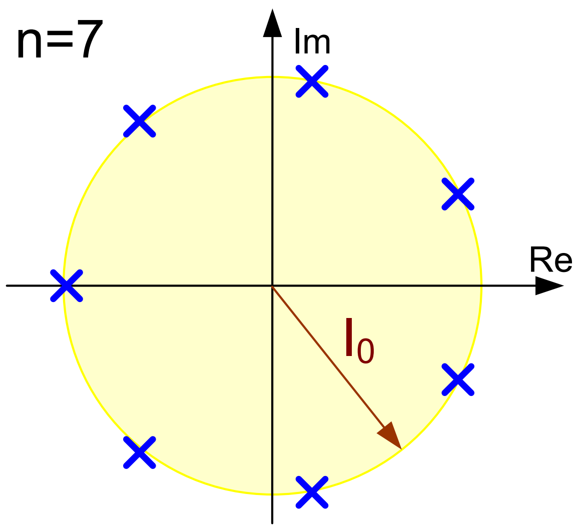


General form of response for odd number of poles:

$$A_0 e^{\alpha_0 t} + \sum_{i=1}^{n/2} |A_i| e^{\alpha_i t} \cos(\beta_i t + \theta_i)$$

The impulse response (for n=7) will have two decaying exponential terms and two growing exponential terms

What will happen with a circuit that has two pole-pairs in the RHP?



-0.62349	-0.781831482
0.222521	-0.974927912
0.900969	-0.433883739
0.900969	0.433883739
0.222521	0.974927912
-0.62349	0.781831482
-1	3.67545E-16

$\alpha_1=0.2225$ $\beta_1=0.974$

$\alpha_2=0.9009$ $\beta_2=0.4338$

Consider the growing exponential terms and normalize to $I_0=1$

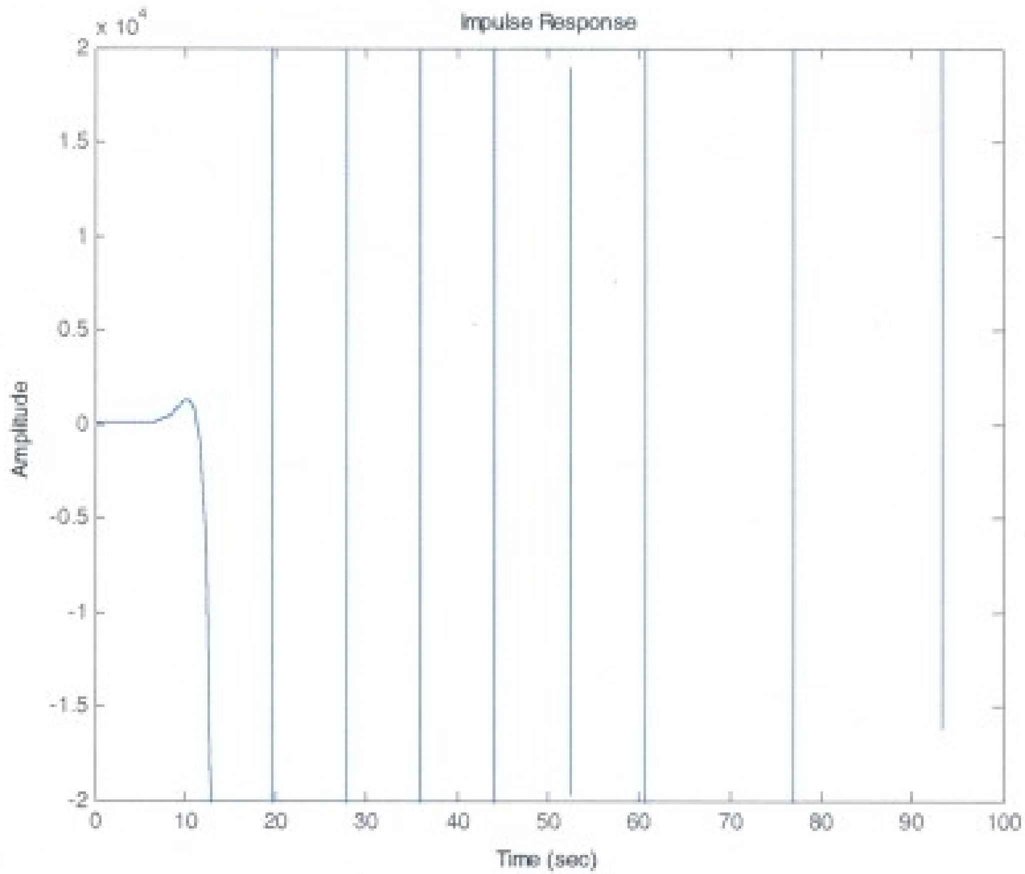
$$|A_1|e^{\alpha_1 t}\cos(\beta_1 t+\theta_1) + |A_2|e^{\alpha_2 t}\cos(\beta_2 t+\theta_2)$$

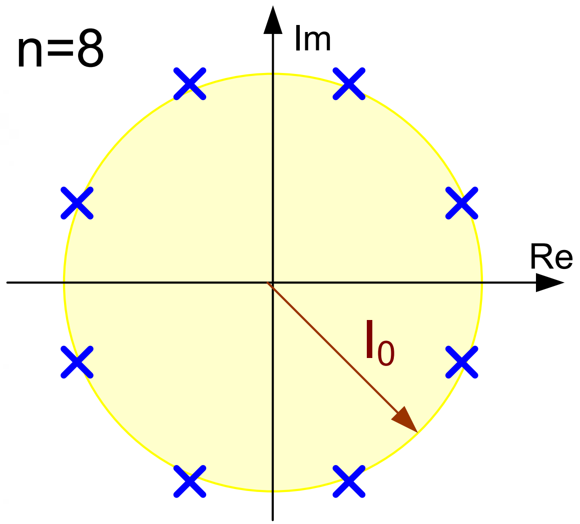
At t=145 (after only 10 periods of the lower frequency signal)

$$r = \left.\frac{e^{\alpha_2 t}}{e^{\alpha_1 t}}\right|_{t=145} = \frac{e^{.9009 \bullet 145}}{e^{.2225 \bullet 145}} = 5.2\text{x}10^{42}$$

The lower frequency oscillation will completely dominate !

What will happen with a circuit that has two pole-pairs in the RHP?





Thanks to Chen for these plots

Figure 14 N=8 impulse response

Can only see the lower frequency component !

What will happen with a circuit that has two pole-pairs in the RHP?

Thanks to Chen for these plots

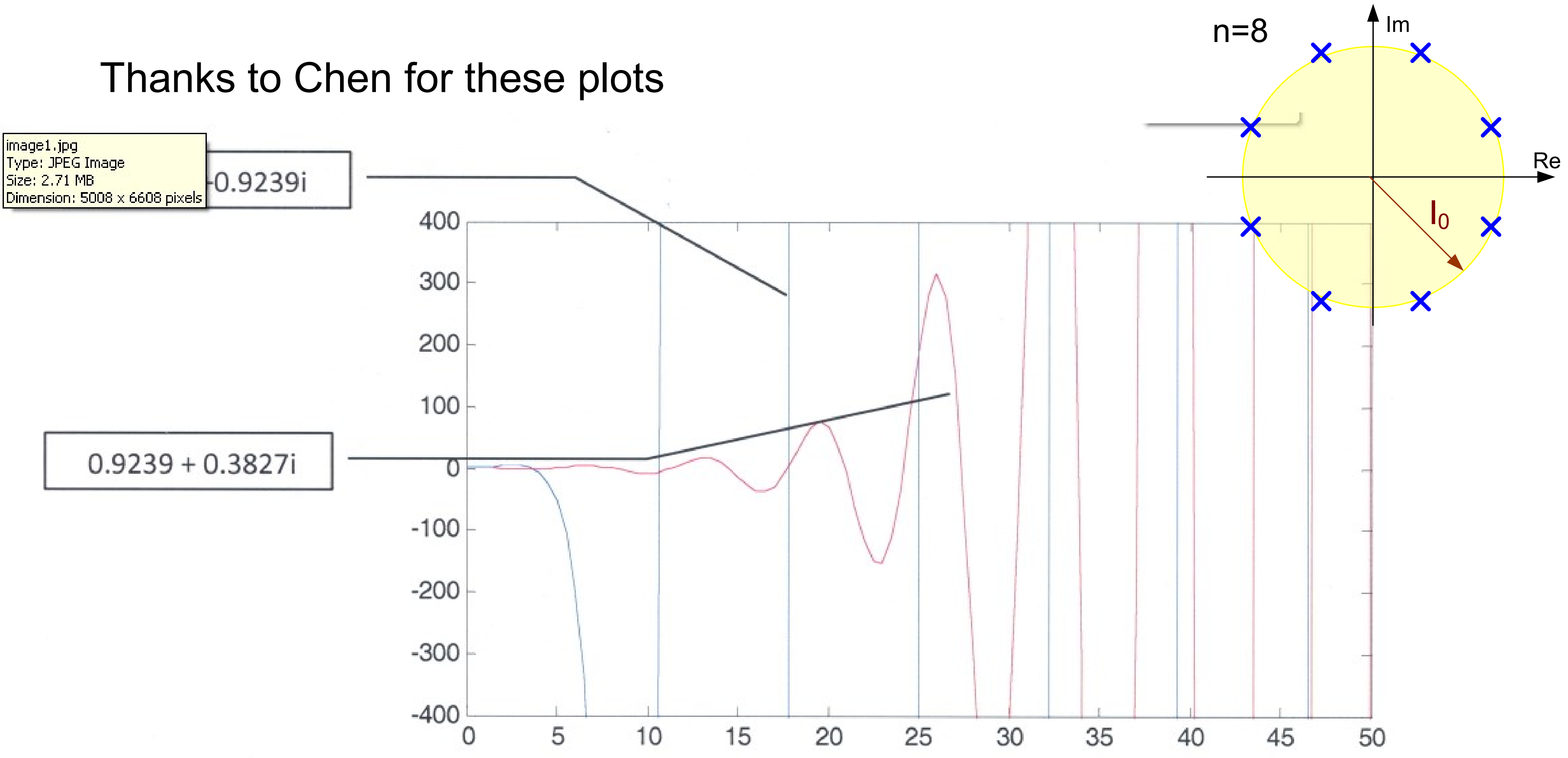
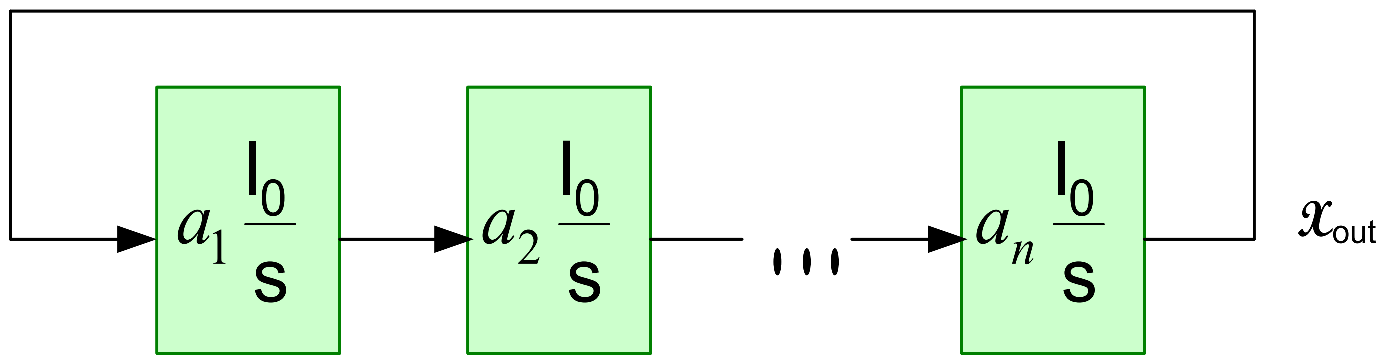


Figure 7 N=8 the impulse response of two poles

After even only two periods of the lower frequency waveform, it completely dominates !

How do we guarantee that we have a net coefficient of +1 in D(s)?

$$D(s) = s^n + I_0^n$$



$$x_{out} = \left(\prod_{i=1}^{n} a_i \left(\frac{I_0}{s} \right) \right) x_{out} \qquad a_i \in \{-1, 1\}$$

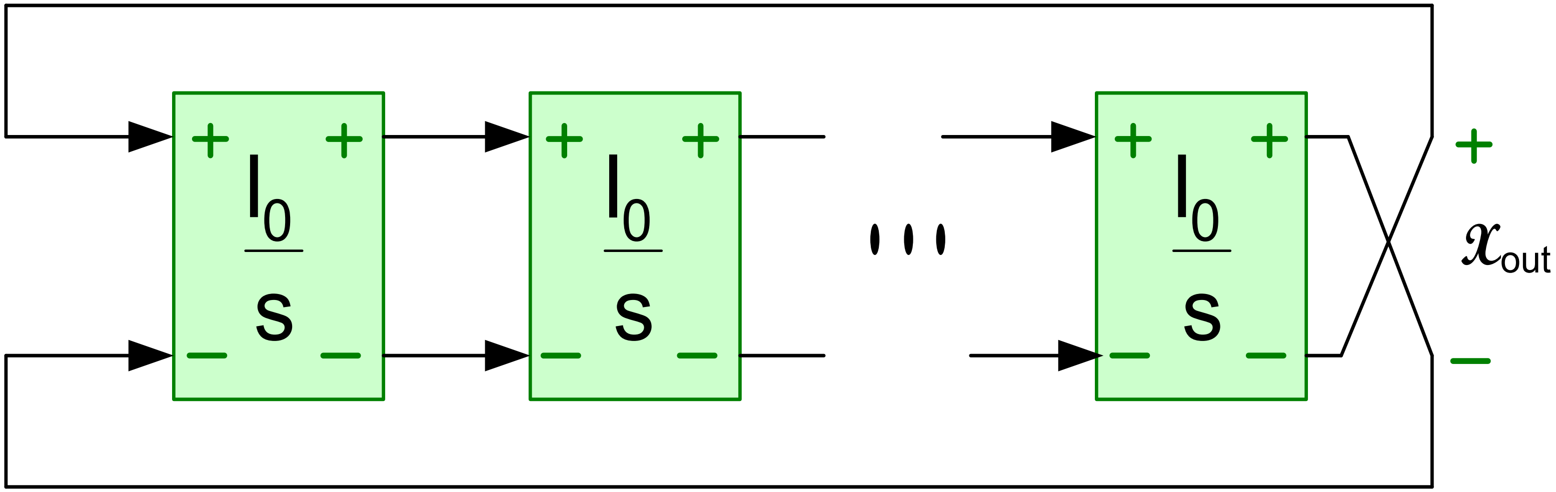
$$D(s) = s^n - \left(\prod_{i=1}^{n} a_i \right) I_0^n \longrightarrow \prod_{i=1}^{n} a_i = -1$$

Must have an odd number of inversions in the loop !

If n is odd, all stages can be inverting and identical !

How do we guarantee that we have a net coefficient of +1 in D(s)?

$$D(s) = s^n + I_0^n$$



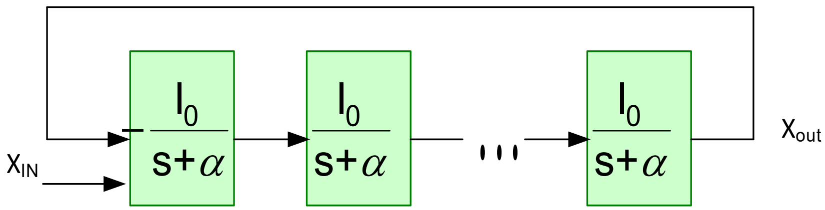
If fully differential or fully balanced, must have an odd number of crossings of outputs

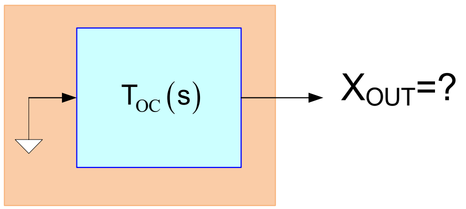
Applicable for both even and odd order loops

Inputs to Oscillator-Derived Filters:

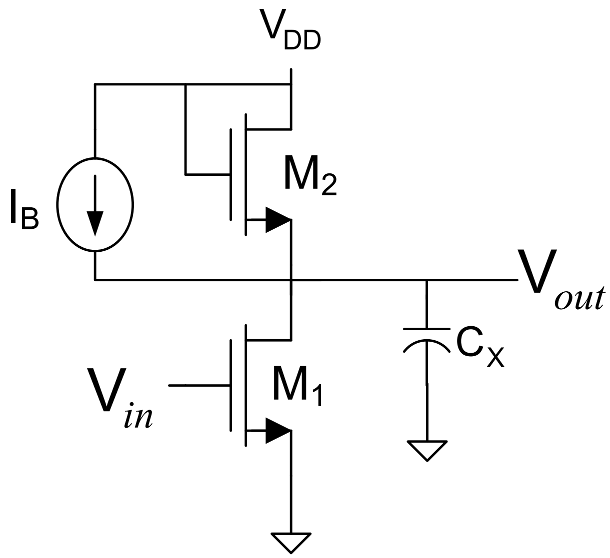
Most applicable to designing 2nd-order high frequency narrow band bandpass filters

- Add loss to delay stages
- Multiple Input Locations Often Possible
- Natural Input is Input to delay stage





A lossy integrator stage

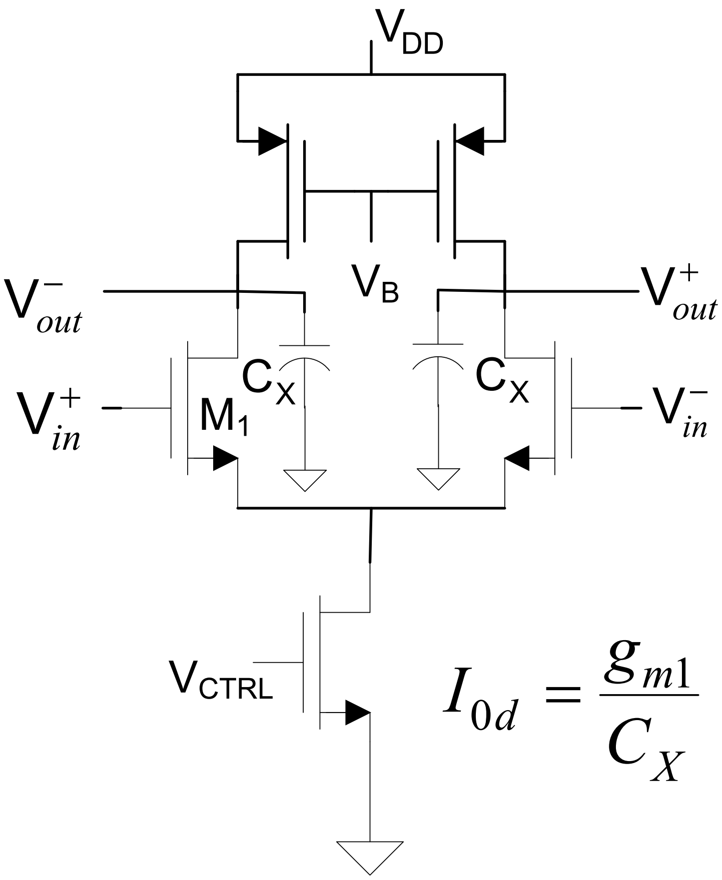


$$I(s) = \frac{-g_{m1}/C_X}{s+g_{m2}/C_X}$$

$$I_0 = g_{m1}/C_X$$

$$\alpha_L = g_{m2}/C_X$$

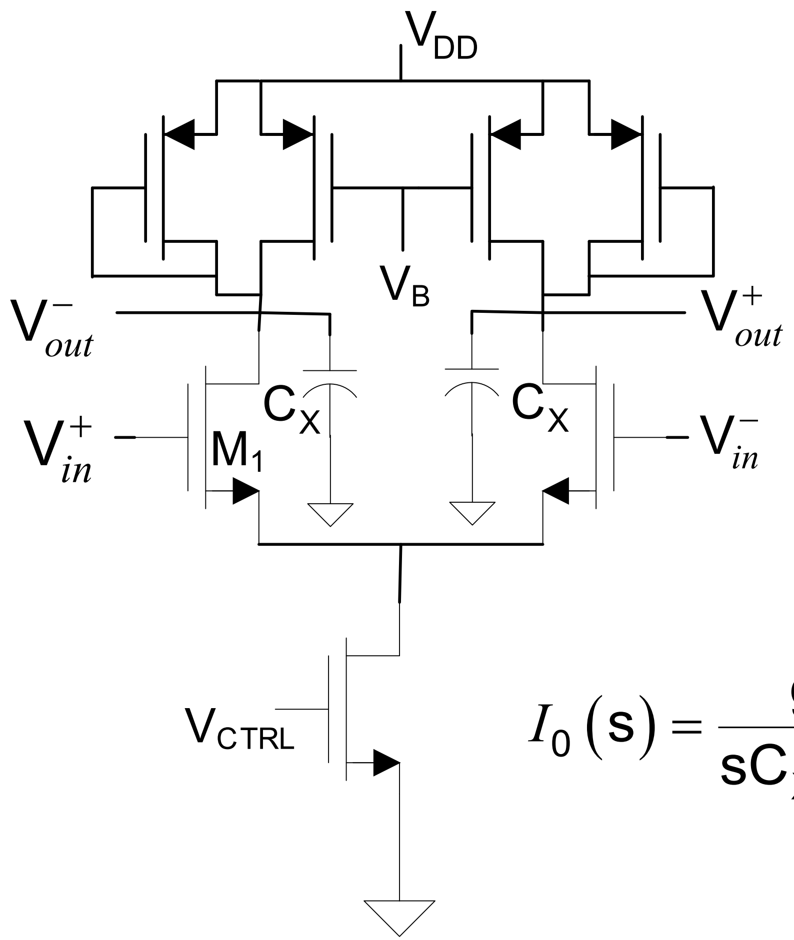
A fully-differential voltage-controlled integrator stage



$$I_{0d} = \frac{g_{m1}}{C_X}$$

Will need CMFB circuit

A fully-differential voltage-controlled integrator stage with loss

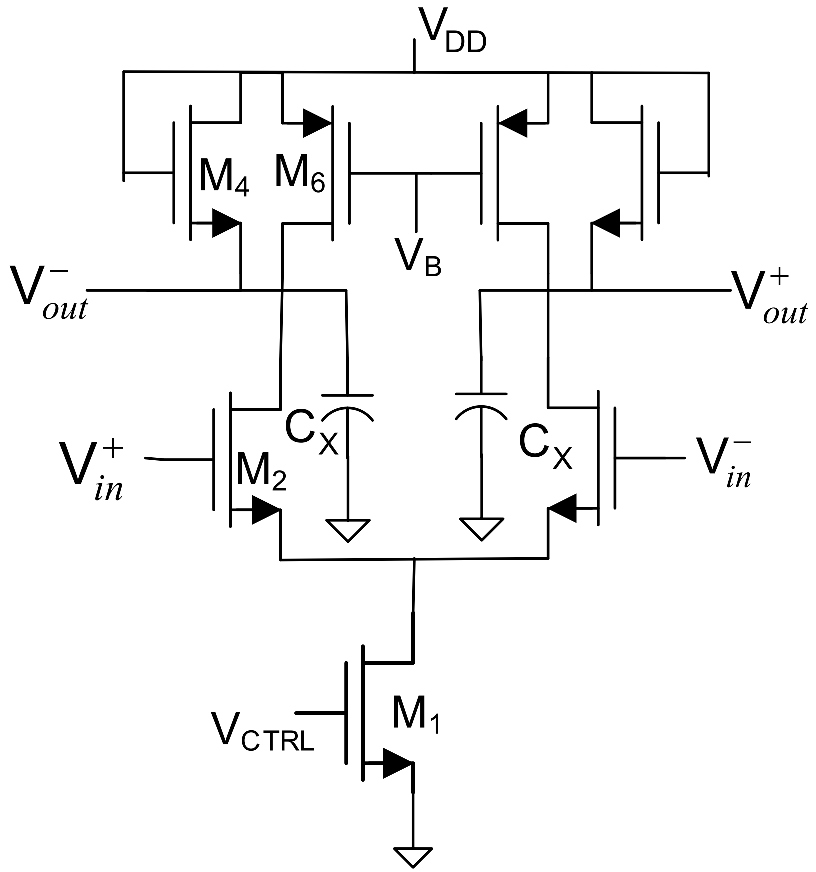


$$I_0(s) = \frac{g_{m1}}{sC_X + g_{m3}}$$

Will need CMFB circuit

A fully-differential voltage-controlled integrator stage with loss

(almost same as previous)

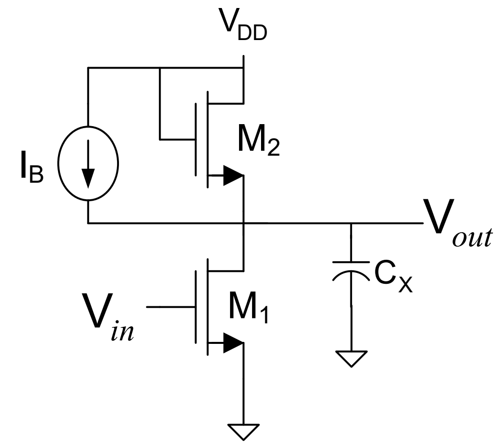


$$I_0(s) = \frac{g_{m1}}{sC_X + g_{m3}}$$

Will need CMFB circuit

Example:

Using the single-stage lossy integrator, design the integrator to meet a given ω_0 and Q requirement



Recall:

$$I_0 = \frac{\omega_0}{(\sin\theta)2Q}\sqrt{4Q^2-1} \qquad (1)$$

$$\alpha_L = \frac{\omega_0}{2Q} + \frac{\omega_0}{2Q(\tan\theta)}\sqrt{4Q^2-1} \qquad (2)$$

$$V_{OUT}(sC_x + g_{m2}) + g_{m1}V_{IN} = 0$$

$$\frac{V_{OUT}}{V_{IN}} = -\frac{g_{m1}}{sC_x + g_{m2}}$$

Substituting for I_0 and α_L we obtain:

$$\frac{g_{m1}}{C_X} = \frac{\omega_0}{(\sin\theta)2Q}\sqrt{4Q^2-1} \qquad (3)$$

$$\frac{g_{m2}}{C_X} = \frac{\omega_0}{2Q} + \frac{\omega_0}{2Q(\tan\theta)}\sqrt{4Q^2-1} \qquad (4)$$

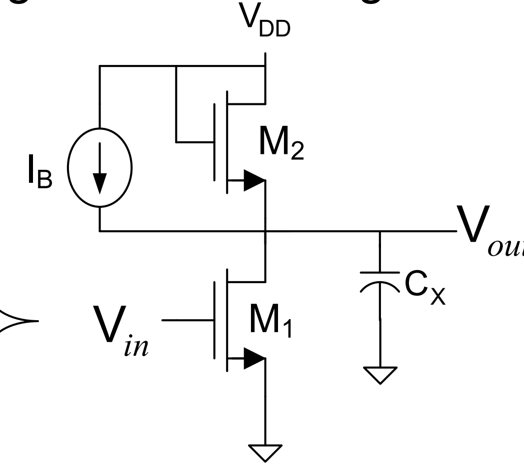
$$I_0 = g_{m1}/C_X$$

$$\alpha_L = g_{m2}/C_X$$

Unknowns: $I_B, V_{EB1}, W_1/L_1, W_2/L_2, C_X$

Example:

Using the single-stage lossy integrator, design the integrator to meet a given ω_0 and Q requirement



Expressing g_{m1} and g_{m2} in terms of design parameters:

$$\frac{\mu C_{OX} W_1 V_{EB1}}{L_1 C_X} = \frac{\omega_0}{(\sin\theta) 2Q}\sqrt{4Q^2-1} \qquad (5)$$

$$\frac{\mu C_{OX} W_2 V_{EB2}}{L_2 C_X} = \frac{\omega_0}{2Q} + \frac{\omega_0}{2Q(\tan\theta)}\sqrt{4Q^2-1} \qquad (6)$$

$$I_0 = g_{m1}/C_X$$

$$\alpha_L = g_{m2}/C_X$$

If we assume I_B=0, equating drain currents obtain:

$$V_{EB2} = V_{EB1}\sqrt{\frac{W_1 L_2}{W_2 L_1}} \qquad (7)$$

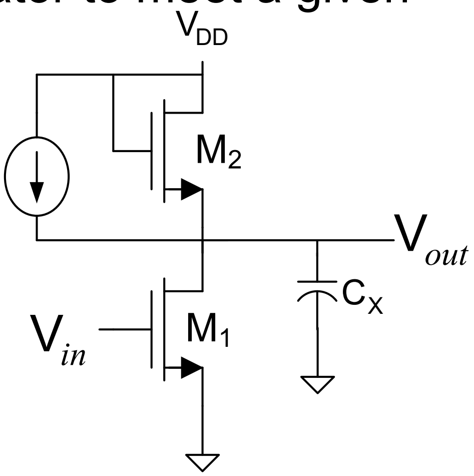
Thus the previous two expressions can be rewritten as :

$$\frac{\mu C_{OX} V_{EB1}}{C_X}\left[\frac{W_1}{L_1}\right] = \frac{\omega_0}{(\sin\theta) 2Q}\sqrt{4Q^2-1} \qquad (8)$$

$$\frac{\mu C_{OX} V_{EB1}}{C_X}\left[\frac{W_1 W_2}{L_1 L_2}\right] = \frac{\omega_0}{2Q} + \frac{\omega_0}{2Q(\tan\theta)}\sqrt{4Q^2-1} \qquad (9)$$

Example:

Using the single-stage lossy integrator, design the integrator to meet a given ω_0 and Q requirement



$$\frac{\mu C_{OX} V_{EB1}}{C_X}\left[\frac{W_1}{L_1}\right] = \frac{\omega_0}{(\sin\theta)2Q}\sqrt{4Q^2\text{-}1} \qquad (8)$$

$$\frac{\mu C_{OX} V_{EB1}}{C_X}\left[\frac{W_1 W_2}{L_1 L_2}\right] = \frac{\omega_0}{2Q} + \frac{\omega_0}{2Q(\tan\theta)}\sqrt{4Q^2\text{-}1} \qquad (9)$$

$$I_0 = g_{m1}/C_X$$

$$\alpha_L = g_{m2}/C_X$$

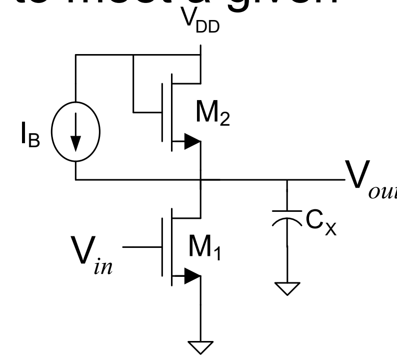
Taking the ratio of these two equations we obtain:

$$\frac{W_2}{L_2} = \frac{\sin\theta + \cos\theta\sqrt{4Q^2\text{-}1}}{\sqrt{4Q^2\text{-}1}} \qquad (10)$$

Observe that the pole Q is determined by the dimensions of the lossy device !

Example:

Using the single-stage lossy integrator, design the integrator to meet a given ω_0 and Q requirement



$$\frac{\mu C_{OX} V_{EB1}}{C_X}\left[\frac{W_1}{L_1}\right]=\frac{\omega_0}{(\sin\theta)2Q}\sqrt{4Q^2\text{-}1} \qquad (8)$$

$$\frac{W_2}{L_2}=\frac{\sin\theta+\cos\theta\sqrt{4Q^2\text{-}1}}{\sqrt{4Q^2\text{-}1}} \qquad (10)$$

Still must obtain W_1/ L_1, V_{EB1}, and C_X from either of these equations

Although it appears that there might be 3 degrees of freedom left and only one constraint (one of these equations), if these integrators are connected in a loop, the operating point (Q-point) will be the same for all stages and will be that value where $V_{out}=V_{in}$. So, this adds a second constraint.

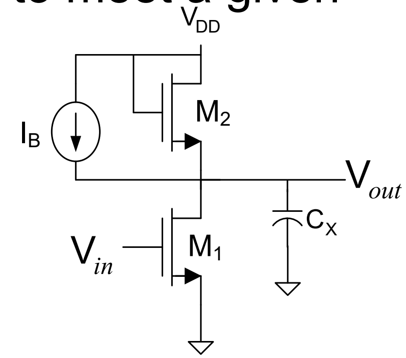
Setting $V_{out}=V_{in}$, and assuming $V_{T1}=V_{T2}$, we obtain from KVL

$$V_{DD}=V_{EB1}+V_{EB2}+2V_T \qquad (11)$$

But V_{EB1} and V_{EB2} are also related in (7)

Example:

Using the single-stage lossy integrator, design the integrator to meet a given ω_0 and Q requirement



$$\frac{\mu C_{OX} V_{EB1}}{C_X}\left[\frac{W_1}{L_1}\right]=\frac{\omega_0}{(\sin\theta)2Q}\sqrt{4Q^2\text{-}1} \qquad (8)$$

$$\frac{W_2}{L_2}=\frac{\sin\theta+\cos\theta\sqrt{4Q^2\text{-}1}}{\sqrt{4Q^2\text{-}1}} \qquad (10)$$

Still must obtain W_1/L_1, V_{EB1}, and C_X from either of these equations

$$V_{DD}=V_{EB1}+V_{EB2}+2V_T \qquad (11)$$

$$V_{EB2}=V_{EB1}\sqrt{\frac{W_1L_2}{W_2L_1}} \qquad (7)$$

$\rightarrow$

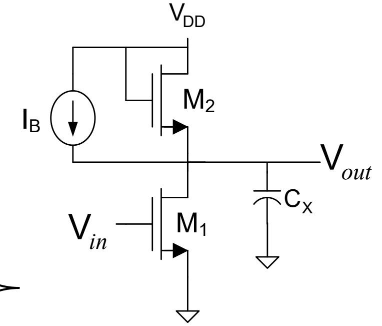
$$V_{EB1}=\frac{V_{DD}\text{-}2V_T}{1+\sqrt{\frac{W_2L_1}{W_1L_2}}} \qquad (12)$$

Substituting (10) into (12) and then into (8) we obtain

$$\frac{\mu C_{OX}}{C_X}\left[\frac{W_1}{L_1}\right]\left(\frac{V_{DD}-2V_T}{1+\sqrt{\left(\frac{W_1}{L_1}\right)^{-1}\left(\frac{\sin\theta+\cos\theta\sqrt{4Q^2\text{-}1}}{\sqrt{4Q^2\text{-}1}}\right)}}\right)=\frac{\omega_0}{(\sin\theta)2Q}\sqrt{4Q^2\text{-}1} \qquad (13)$$

Example:

Using the single-stage lossy integrator, design the integrator to meet a given ω_0 and Q requirement



$$\frac{W_2}{L_2}=\frac{\sin\theta+\cos\theta\sqrt{4Q^2\text{-}1}}{\sqrt{4Q^2\text{-}1}} \qquad (10)$$

$$\frac{\mu C_{OX}}{C_X}\left[\frac{W_1}{L_1}\right]\left(\frac{V_{DD}-2V_T}{1+\sqrt{\left(\frac{W_1}{L_1}\right)^{-1}\left(\frac{\sin\theta+\cos\theta\sqrt{4Q^2\text{-}1}}{\sqrt{4Q^2\text{-}1}}\right)}}\right)=\frac{\omega_0}{(\sin\theta)2Q}\sqrt{4Q^2\text{-}1} \qquad (13)$$

There is still one degree of freedom remaining. Can either pick W_1/L_1 and solve for C_X or pick C_X and solve for W_1/L_1.

Explicit expression for W_1/L_1 not available

Tradeoffs between C_X and W_1/L_1 will often be made

Since $V_{OUTQ}=V_T+V_{EB1}$, it may be preferred to pick V_{EB1}, then solve (12) for W_1/L_1 and then solve (13) for C_X

Adding I_B will provide one additional degree of freedom (we arbitrarily set it to 0 in this analysis) and will relax the relationship between V_{OUTQ} and W_1/L_1 since (7) will be modified

Stay Safe and Stay Healthy !

End of Lecture 36